

# An Immersed Boundary Method with Divergence-Free Velocity Interpolation

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May 11, 2015

## A 2D pumping membrane

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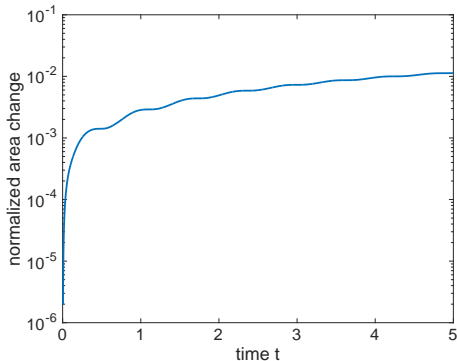
- ▷ A perturbed circular membrane immersed in a viscous incompressible fluid

$$\mathbf{X}(s) = (1 + \epsilon \cos ps)(\cos(s), \sin(s)), \quad p = 2$$

- ▷ Lagrangian force density  $\mathbf{F} = K(t) \frac{\partial^2 \mathbf{X}}{\partial s^2}$ , stiffness  $K(t) = K_c(1 + \tau \sin(\omega_0 t))$

⇒ parametric resonance (Cortez et al. 2004)

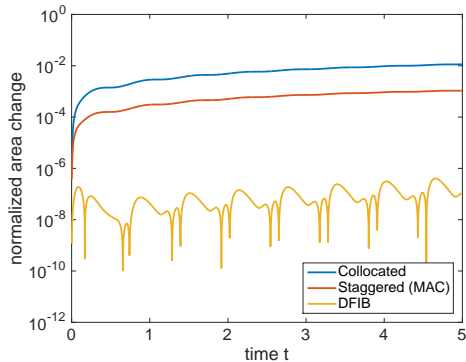
- ▷ Standard IB method + collocated-grid fluid solver ⇒ **substantial volume loss!**



## Work on improving volume conservation

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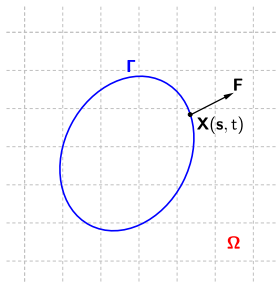
- ▷ Modified discrete divergence operator (Peskin & Printz 1993)
- ▷ Staggered-grid fluid solver (Griffith 2012)
- ▷ Divergence-free velocity interpolation & force spreading (DFIB, Peskin)



## Equations of motion

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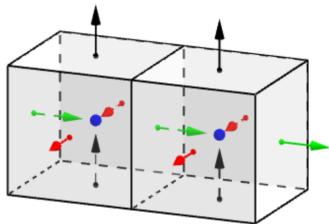
$$\begin{aligned}\rho \left( \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) + \nabla p &= \mu \Delta \mathbf{v} + \mathbf{f} \\ \nabla \cdot \mathbf{v} &= 0 \\ \mathbf{f}(\mathbf{x}, t) &= \int_{\Gamma} \mathbf{F}(\mathbf{s}, t) \delta(\mathbf{x} - \mathbf{X}(\mathbf{s}, t)) ds \\ \frac{\partial \mathbf{X}}{\partial t} &= \int_{\Omega} \mathbf{v}(\mathbf{x}, t) \delta(\mathbf{x} - \mathbf{X}(\mathbf{s}, t)) d\mathbf{x} \\ \mathbf{F}(\mathbf{s}, t) &= \mathcal{F}(\mathbf{X}(\mathbf{s}, t), t)\end{aligned}$$



- ▷  $\Omega$  : fluid domain,  $\mathbf{x}$  : Eulerian
- ▷  $\Gamma$  : structure,  $\mathbf{s}$  : Lagrangian
- ▷  $\mathbf{F}$  : force density on structure
- ▷ Navier-Stokes + fluid-structure coupling via the  $\delta$ -function

## Spatial Discretization

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- ▷ Periodic domain:  $[0, L]^3$   
Meshwidth:  $h = L/N$
- ▷ Staggered-grid discretization:  
Pressure  $p$ : **cell-centered**  
Velocity  $\mathbf{u}$ : **face-centered**

- ▷ Discrete partial derivative of grid function  $\varphi$ :

$$D_{\alpha}^h \varphi := \frac{\varphi(\mathbf{x} + \frac{h}{2} \mathbf{e}_{\alpha}) - \varphi(\mathbf{x} - \frac{h}{2} \mathbf{e}_{\alpha})}{h}, \quad \alpha = 1, 2, 3.$$

Discrete gradient:  $\mathbf{D}^h \varphi := (D_1^h \varphi, D_2^h \varphi, D_3^h \varphi)$

Discrete divergence:  $\mathbf{D}^h \cdot \mathbf{u} := \sum_{\alpha=1}^3 D_{\alpha}^h u_{\alpha}$ ,

Discrete Laplacian:  $L^h \varphi = (\mathbf{D}^h \cdot \mathbf{D}^h) \varphi$

## Spatial discretization

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$$\begin{aligned}\rho \left( \frac{d\mathbf{u}}{dt} + \mathbf{N}(\mathbf{u}) \right) + \mathbf{D}^h p &= \mu L^h \mathbf{u} + \mathbf{f} \\ \mathbf{D}^h \cdot \mathbf{u} &= 0 \\ \mathbf{f} &= \mathcal{S}[\mathbf{X}]\mathbf{F} \\ \mathbf{U}_k &= \frac{d\mathbf{X}_k}{dt} = \mathcal{S}^*[\mathbf{X}_k]\mathbf{u} \\ \mathbf{F}_k &= \mathbf{F}(\mathbf{X}_k) = \mathcal{F}(\mathbf{X}_k, t)\end{aligned}$$

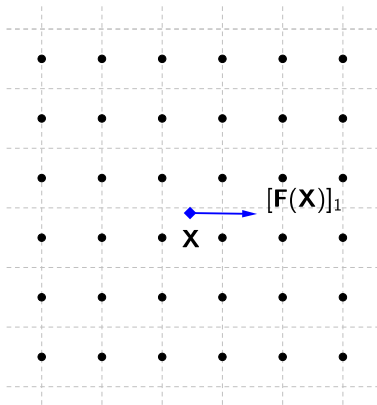
Lagrangian markers:  $\mathbf{X} = \{\mathbf{X}_1, \dots, \mathbf{X}_M\}$ ,  $\mathbf{F} = \{\mathbf{F}_1, \dots, \mathbf{F}_M\}$

▷ Standard IB force spreading:  $\mathbf{f}(\mathbf{x}) = \mathcal{S}[\mathbf{X}]\mathbf{F} = \sum_{k=1}^M \mathbf{F}_k \delta_h(\mathbf{x} - \mathbf{X}_k) \Delta \mathbf{s}_k$

Standard IB velocity interpolation:  $\mathbf{U}_k = \mathcal{S}^*[\mathbf{X}_k]\mathbf{u} = \sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \delta_h(\mathbf{x} - \mathbf{X}_k) h^3$

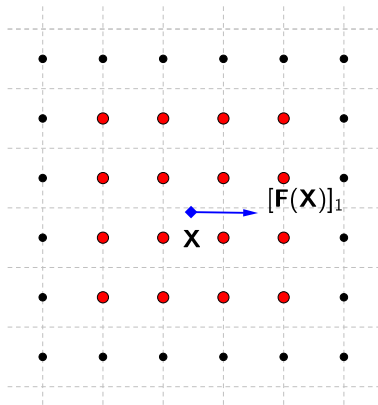
▷ Power identity (adjointness):  $\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k \cdot \mathbf{U}_k$

## Standard IB force spreading & velocity interpolation \_\_\_\_\_



- ▷  $\mathbf{u}$  divergence-free in the discrete sense:  $\mathbf{D}^h \cdot \mathbf{u} = 0$
- ▷  $\mathbf{X}$ : any arbitrary point in domain

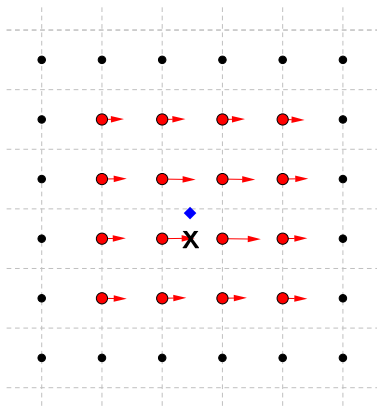
## Standard IB force spreading & velocity interpolation \_\_\_\_\_



- ▷  $\mathbf{u}$  divergence-free in the discrete sense:  $\mathbf{D}^h \cdot \mathbf{u} = 0$
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 $\delta_h$ : 4-point discrete delta kernel

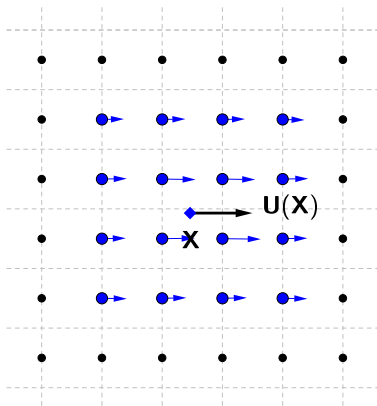


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- ▷  $\mathbf{X}$ : any arbitrary point in domain  
 $\delta_h$ : 4-point discrete delta kernel
- ▷ Force spreading:  
 $\mathbf{f}(\mathbf{x}) = \mathbf{F}\delta_h(\mathbf{x} - \mathbf{X})$

## Standard IB force spreading & velocity interpolation \_\_\_\_\_



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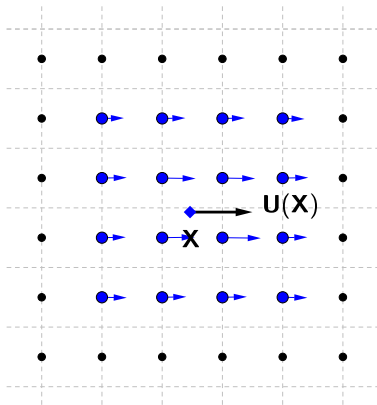
▷ Force spreading:

$$\mathbf{f}(\mathbf{x}) = \mathbf{F} \delta_h(\mathbf{x} - \mathbf{X})$$

▷ Velocity interpolation:

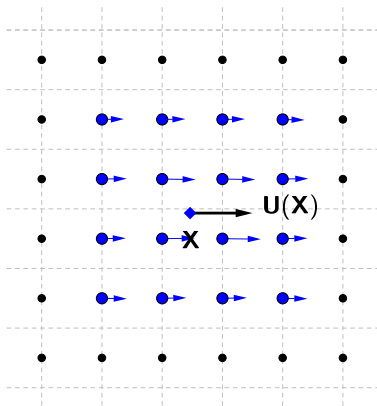
$$\mathbf{U}(\mathbf{X}) = \sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \delta_h(\mathbf{x} - \mathbf{X}) h^3$$

## Standard IB force spreading & velocity interpolation \_\_\_\_\_



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$$\mathbf{U}(\mathbf{X}) = \sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \delta_h(\mathbf{x} - \mathbf{X}) h^3$$
- ▷ spreading & interpolation: **local!**

## Standard IB force spreading & velocity interpolation \_\_\_\_\_



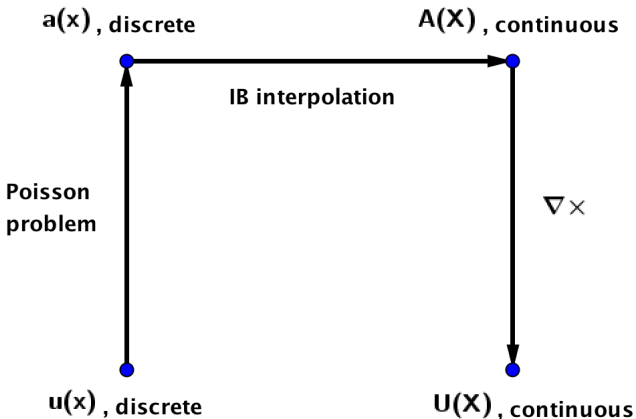
- ▷  $\mathbf{u}$  divergence-free in the discrete sense:  $\mathbf{D}^h \cdot \mathbf{u} = 0$
- ▷  $\mathbf{X}$ : any arbitrary point in domain  
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- ▷ Force spreading:  
 $\mathbf{f}(\mathbf{x}) = \mathbf{F} \delta_h(\mathbf{x} - \mathbf{X})$
- ▷ Velocity interpolation:  

$$\mathbf{U}(\mathbf{X}) = \sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \delta_h(\mathbf{x} - \mathbf{X}) h^3$$
- ▷ spreading & interpolation: **local!**

▷  $\mathbf{U}(\mathbf{X})$  is not divergence-free in the continuous sense,

## Divergence-free velocity interpolation \_\_\_\_\_

- ▷ **Challenge:** given  $\mathbf{u}(\mathbf{x})$  that is discretely divergence-free, how to construct  $\mathbf{U}(\mathbf{X})$  that is continuously divergence-free?
- ▷ **Idea:**  $\mathbf{U}(\mathbf{X}) = (\nabla \times \mathbf{A})(\mathbf{X})$ , where  $\mathbf{A}(\mathbf{X})$  is the vector potential of  $\mathbf{U}(\mathbf{X})$ .



## Divergence-free velocity interpolation

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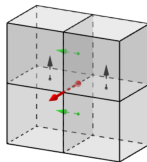
- ▷ First, construct a discrete vector potential  $\mathbf{a}(\mathbf{x})$  by solving

$$\begin{cases} \mathbf{u} - \mathbf{u}_0 &= \mathbf{D}^h \times \mathbf{a} \\ 0 &= \mathbf{D}^h \cdot \mathbf{a} \end{cases} \implies -(\mathbf{D}^h \cdot \mathbf{D}^h)\mathbf{a} = \mathbf{D}^h \times \mathbf{u} \quad (\text{FFT!}) \quad (1)$$

where  $\mathbf{u}_0$  is the mean of  $\mathbf{u}$  and the gauge condition:  $\mathbf{D}^h \cdot \mathbf{a} = 0$

- ▷ Question: where is  $\mathbf{a}(\mathbf{x})$  defined on the staggered grid? **edge-centered!**

For example,  $[\mathbf{a}(\mathbf{x})]_1 = D_2^h u_3 - D_3^h u_2$



- ▷ Next, interpolate  $\mathbf{a}(\mathbf{x})$  to get  $\mathbf{A}(\mathbf{X})$  via standard IB interpolation,

$$\mathbf{A}(\mathbf{X}) = \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \delta_h(\mathbf{x} - \mathbf{X}) h^3.$$

- ▷ Finally,  $\mathbf{U}(\mathbf{X}) = \mathbf{u}_0 + (\nabla \times \mathbf{A})(\mathbf{X}) = \mathbf{u}_0 + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \times (\nabla \delta_h)(\mathbf{x} - \mathbf{X}) h^3.$
- ▷ This ensures that  $\nabla \cdot \mathbf{U} = 0.$

## Divergence-free force spreading

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- ▷ **Goal:** seek force spreading  $\mathbf{f}$  that preserves the power identity

$$\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k \cdot \mathbf{U}_k$$

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▷ 
$$\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \mathbf{u}_0 \cdot \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3 + \sum_{\mathbf{x}} (\mathbf{D}^h \times \mathbf{a})(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3$$



## Divergence-free force spreading

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$$\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k \cdot \mathbf{U}_k$$

$$\begin{aligned} \text{▷ } \sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 &= \mathbf{u}_0 \cdot \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3 + \sum_{\mathbf{x}} (\mathbf{D}^h \times \mathbf{a})(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 \\ &= \mathbf{u}_0 \cdot \mathbf{f}_0 V + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \cdot (\mathbf{D}^h \times \mathbf{f})(\mathbf{x}) h^3, \end{aligned}$$

$$\text{where } \mathbf{f}_0 = \frac{1}{V} \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3.$$

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where  $\mathbf{f}_0 = \frac{1}{V} \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3$ .

$$\triangleright \sum_{k=1}^M \mathbf{U}_k \cdot \mathbf{F}_k = \mathbf{u}_0 \cdot \sum_{k=1}^M \mathbf{F}_k + \sum_{k=1}^M \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \times (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \cdot \mathbf{F}_k h^3$$

## Divergence-free force spreading

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$$\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k \cdot \mathbf{U}_k$$

$$\begin{aligned} \triangleright \sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 &= \mathbf{u}_0 \cdot \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3 + \sum_{\mathbf{x}} (\mathbf{D}^h \times \mathbf{a})(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 \\ &= \mathbf{u}_0 \cdot \mathbf{f}_0 V + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \cdot (\mathbf{D}^h \times \mathbf{f})(\mathbf{x}) h^3, \end{aligned}$$

where  $\mathbf{f}_0 = \frac{1}{V} \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3$ .

$$\begin{aligned} \triangleright \sum_{k=1}^M \mathbf{U}_k \cdot \mathbf{F}_k &= \mathbf{u}_0 \cdot \sum_{k=1}^M \mathbf{F}_k + \sum_{k=1}^M \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \times (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \cdot \mathbf{F}_k h^3 \\ &= \mathbf{u}_0 \cdot \sum_{k=1}^M \mathbf{F}_k + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \cdot \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k h^3. \end{aligned}$$

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where  $\mathbf{f}_0 = \frac{1}{V} \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3$ .

$$\begin{aligned} \triangleright \sum_{k=1}^M \mathbf{U}_k \cdot \mathbf{F}_k &= \mathbf{u}_0 \cdot \sum_{k=1}^M \mathbf{F}_k + \sum_{k=1}^M \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \times (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \cdot \mathbf{F}_k h^3 \\ &= \mathbf{u}_0 \cdot \sum_{k=1}^M \mathbf{F}_k + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \cdot \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k h^3. \end{aligned}$$

## Divergence-free force spreading

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- ▷ **Goal:** seek force spreading  $\mathbf{f}$  that preserves the power identity

$$\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k \cdot \mathbf{U}_k$$

$$\begin{aligned} \text{▷ } \sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 &= \mathbf{u}_0 \cdot \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3 + \sum_{\mathbf{x}} (\mathbf{D}^h \times \mathbf{a})(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 \\ &= \mathbf{u}_0 \cdot \mathbf{f}_0 V + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \cdot (\mathbf{D}^h \times \mathbf{f})(\mathbf{x}) h^3, \end{aligned}$$

where  $\mathbf{f}_0 = \frac{1}{V} \sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3$ .

$$\begin{aligned} \text{▷ } \sum_{k=1}^M \mathbf{U}_k \cdot \mathbf{F}_k &= \mathbf{u}_0 \cdot \sum_{k=1}^M \mathbf{F}_k + \sum_{k=1}^M \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \times (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \cdot \mathbf{F}_k h^3 \\ &= \mathbf{u}_0 \cdot \sum_{k=1}^M \mathbf{F}_k + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \cdot \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k h^3. \end{aligned}$$

▷ want to set  $\mathbf{f}_0 = \frac{1}{V} \sum_{k=1}^M \mathbf{F}_k$  and  $(\mathbf{D}^h \times \mathbf{f})(\mathbf{x}) = \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k$

## Divergence-free force spreading

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- ▷ want to set  $\mathbf{f}_0 = \frac{1}{V} \sum_{k=1}^M \mathbf{F}_k$  and  $(\mathbf{D}^h \times \mathbf{f})(\mathbf{x}) = \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k$

- ▷ The LHS term  $\mathbf{D}^h \cdot (\mathbf{D}^h \times \mathbf{f}) = 0$ , but the RHS term  $\sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k$  is not necessarily discretely divergence-free!

## Divergence-free force spreading

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$$\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k \cdot \mathbf{U}_k$$

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- ▷ The LHS term  $\mathbf{D}^h \cdot (\mathbf{D}^h \times \mathbf{f}) = 0$ , but the RHS term  $\sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k$  is not necessarily discretely divergence-free!
- ▷ To fix this, we can add  $\mathbf{D}^h \varphi$  on the RHS,

$$(\mathbf{D}^h \times \mathbf{f})(\mathbf{x}) = \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k + \mathbf{D}^h \varphi$$

because  $\sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \cdot (\mathbf{D}^h \varphi) h^3 = - \sum_{\mathbf{x}} \left( \mathbf{D}^h \cdot \mathbf{a} \right)^0(\mathbf{x}) \varphi(\mathbf{x}) h^3 = 0$

- ▷ It is also required to add  $\mathbf{D}^h \varphi$  to guarantee the RHS to be discretely divergence-free.

## Divergence-free force spreading

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$$\triangleright \quad (\mathbf{D}^h \times \mathbf{f})(\mathbf{x}) = \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k + \mathbf{D}^h \varphi$$

▷ Option 1: take  $\mathbf{D}^h \cdot$  on both sides, solve a poisson equation of  $\varphi$ . unnecessary

▷ Option 2: take  $\mathbf{D}^h \times$  on both sides,

$$\mathbf{D}^h \times (\mathbf{D}^h \times \mathbf{f}) = \mathbf{D}^h \times \left( \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k \right) + \cancel{\mathbf{D}^h \times (\mathbf{D}^h \varphi)} \rightarrow 0$$

Gauge condition:  $\mathbf{D}^h \cdot \mathbf{f} = 0$

$\Rightarrow$

$$-(\mathbf{D}^h \cdot \mathbf{D}^h) \mathbf{f} = \mathbf{D}^h \times \left( \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k \right), \quad (\text{FFT!})$$

▷ This only determines  $\mathbf{f}$  up to a constant. For uniqueness, we use

$$\sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k.$$



To summarize \_\_\_\_\_

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- ▷ Given  $\mathbf{u}$  that is discretely divergence-free, i.e.,  $\mathbf{D}^h \cdot \mathbf{u} = 0$

Divergence-free velocity interpolation:

1.  $-(\mathbf{D}^h \cdot \mathbf{D}^h) \mathbf{a} = \mathbf{D}^h \times \mathbf{u}$
2.  $\mathbf{U}(\mathbf{X}) = \mathbf{u}_0 + \sum_{\mathbf{x}} \mathbf{a}(\mathbf{x}) \times (\nabla \delta_h)(\mathbf{x} - \mathbf{X}) h^3$

Divergence-free force spreading:

1.  $-(\mathbf{D}^h \cdot \mathbf{D}^h) \mathbf{f} = \mathbf{D}^h \times \left( \sum_{k=1}^M (\nabla \delta_h)(\mathbf{x} - \mathbf{X}_k) \times \mathbf{F}_k \right)$
2.  $\sum_{\mathbf{x}} \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k$

Work added: two poisson problems (FFT!)

New spreading & interpolation  $\implies$  global!

- ▷ Power identity:  $\sum_{\mathbf{x}} \mathbf{u}(\mathbf{x}) \cdot \mathbf{f}(\mathbf{x}) h^3 = \sum_{k=1}^M \mathbf{F}_k \cdot \mathbf{U}_k$

## A new $C^3$ 6-point IB kernel (Peskin)

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$$\delta_h(\mathbf{x}) = \frac{1}{h^3} \phi\left(\frac{x_1}{h}\right) \phi\left(\frac{x_2}{h}\right) \phi\left(\frac{x_3}{h}\right)$$

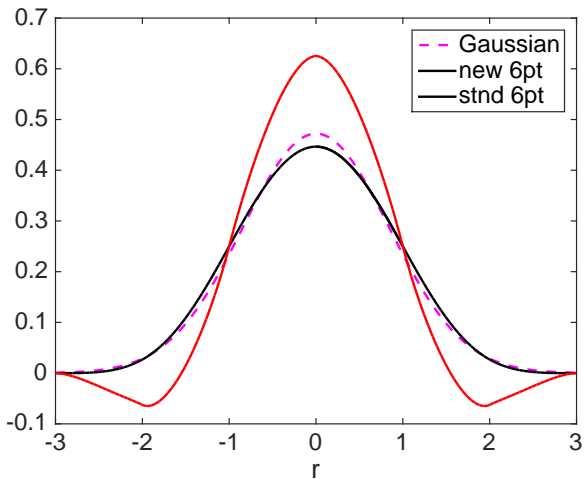
▷ Defining postulates for  $\phi(r)$ :

- (i)  $\phi(r)$  is continuous for all real  $r$ ,
- (ii)  $\phi(r) = 0$  for  $|r| \geq 3$ ,
- (iii)  $\sum_{j \text{ even}} \phi(r-j) = \sum_{j \text{ odd}} \phi(r-j) = \frac{1}{2}$  for all real  $r$ ,
- (iv)  $\sum_j (r-j) \phi(r-j) = 0$ ,
- (v)  $\sum_j (r-j)^2 \phi(r-j) = K$ ,
- (vi)  $\sum_j (r-j)^3 \phi(r-j) = 0$ ,
- (vii)  $\sum_j (\phi(r-j))^2 = C$ .

▷ If  $K = \frac{59}{60} - \frac{\sqrt{29}}{20} \implies \phi$  has three continuous derivatives!

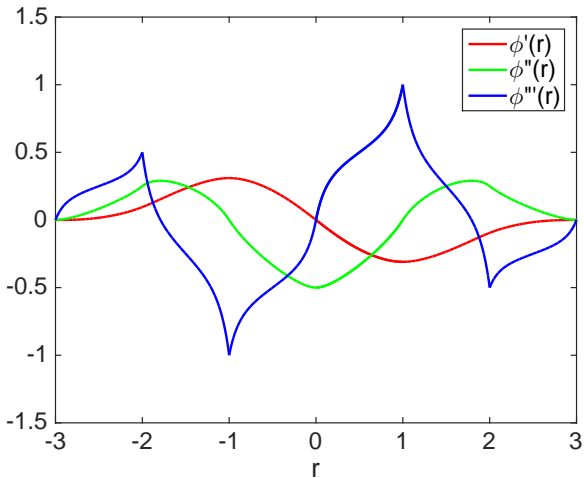
A new  $C^3$  6-point IB kernel (Peskin)

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# A new $C^3$ 6-point IB kernel (Peskin)

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## Test divergence-free velocity interpolation

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- ▷ Taylor vortex:

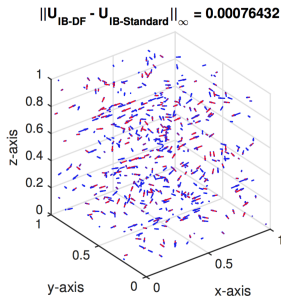
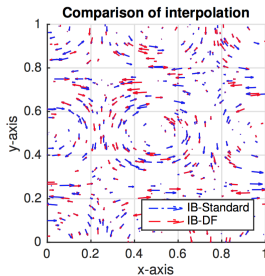
$$v_1 = 2 \cos(2\pi x) \sin(2\pi y) \sin(2\pi z),$$

$$v_2 = -\sin(2\pi x) \cos(2\pi y) \sin(2\pi z),$$

$$v_3 = -\cos(2\pi x) \sin(2\pi y) \cos(2\pi z).$$

- ▷  $\mathbf{u} = \mathbb{P}\mathbf{v}$ , where  $\mathbb{P} = I - \mathbf{D}^h(\mathbf{D}^h \cdot \mathbf{D}^h)^{-1}\mathbf{D}^h$ .

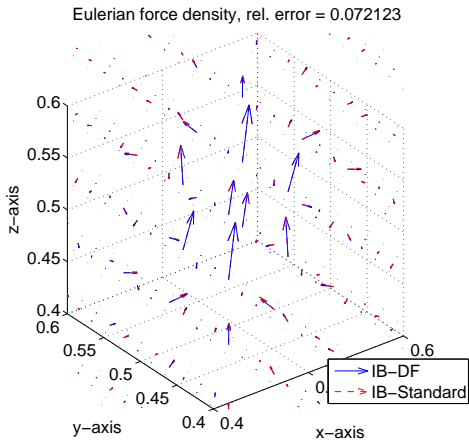
- ▷ interpolate  $\mathbf{U}(\mathbf{X})$  at random  $\mathbf{X}$  from  $\mathbf{u}$



## Test divergence-free force spreading

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Spread a point force  $\mathbf{F} = (1, 1, 1)$  at  $X = (\frac{1}{2}, \frac{1}{2}, \frac{1}{2})$

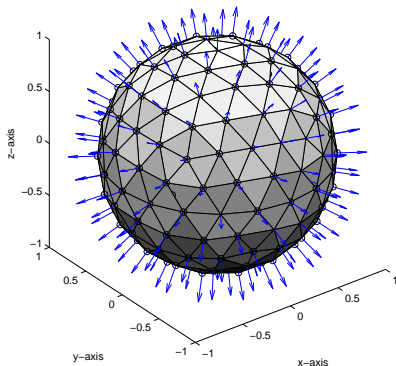


# Test divergence-free force spreading \_\_\_\_\_

Spread surface tension on a triangulated sphere:

$$\mathbf{F}_k = -\frac{\partial \mathcal{E}}{\partial \mathbf{X}_k}, \text{ where } \mathcal{E}[\mathbf{X}_1, \dots, \mathbf{X}_M] = \sum_l A_l$$

Force due to surface tension (-F)



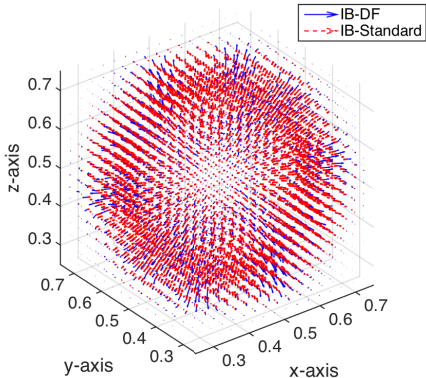
## Test divergence-free force spreading

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Spread surface tension on a triangulated sphere:

$$\mathbf{F}_k = -\frac{\partial \mathcal{E}}{\partial \mathbf{X}_k}, \text{ where } \mathcal{E}[\mathbf{X}_1, \dots, \mathbf{X}_M] = \sum_I A_I$$

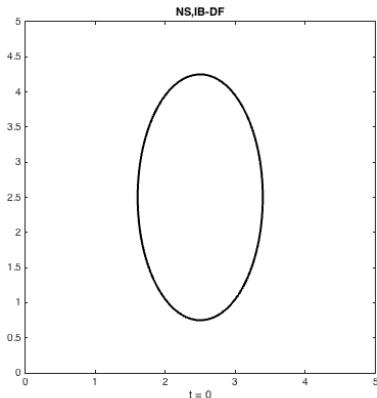
**Eulerian force density, rel. err = 0.99958**  
 $\|f_{\text{IB-DF}}\|_{\infty} = 0.14918, \|f_{\text{IB-Std}}\|_{\infty} = 124.7623$





## A 2D membrane with surface tension \_\_\_\_\_

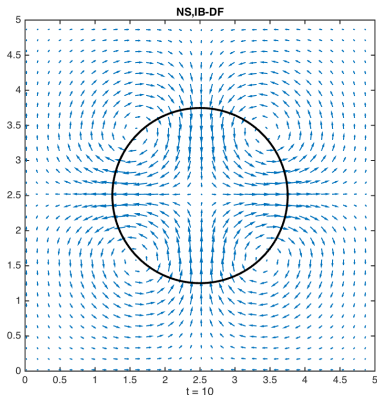
- ▷ Setup: a 2D elliptical membrane immersed in a fluid at rest
- ▷ Surface tension:  $\mathbf{F} = T \frac{\partial \boldsymbol{\tau}}{\partial s}$ , where  $\boldsymbol{\tau} = \frac{\partial \mathbf{X} / \partial s}{|\partial \mathbf{X} / \partial s|}$



## A 2D membrane with surface tension

---

- ▷ Setup: a 2D elliptical membrane immersed in a fluid at rest
- ▷ Surface tension:  $\mathbf{F} = T \frac{\partial \boldsymbol{\tau}}{\partial s}$ , where  $\boldsymbol{\tau} = \frac{\partial \mathbf{X} / \partial s}{|\partial \mathbf{X} / \partial s|}$
- ▷ Parameters:  $\rho = 1, \mu = 0.1, N = 128, L = 5, h = L/N, dt = h/4, T = 2$

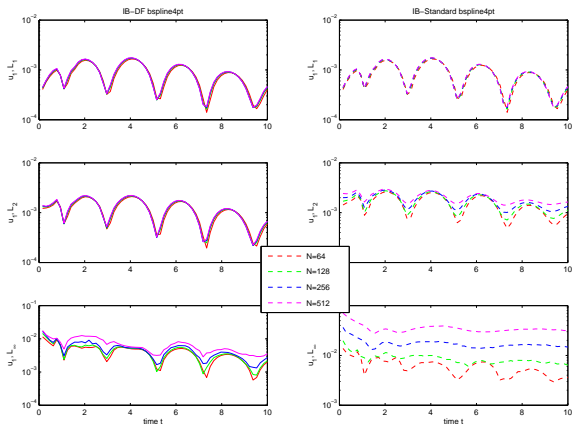


## A 2D membrane with surface tension

---

- ▷ Setup: a 2D elliptical membrane immersed in a fluid at rest
- ▷ Surface tension:  $\mathbf{F} = T \frac{\partial \boldsymbol{\tau}}{\partial s}$ , where  $\boldsymbol{\tau} = \frac{\partial \mathbf{X} / \partial s}{|\partial \mathbf{X} / \partial s|}$
- ▷ 2nd order convergence in  $\mathbf{u}$

Error in the velocity, Factor = 4

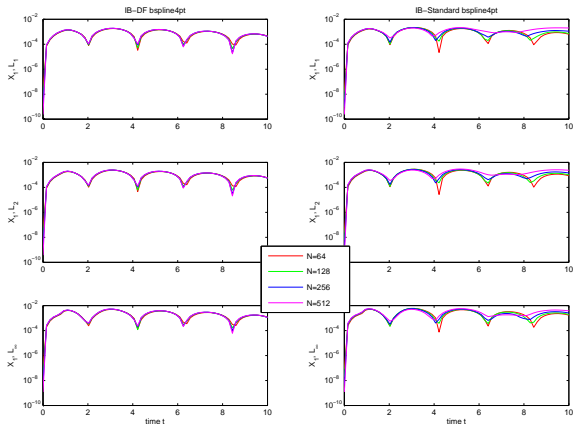


## A 2D membrane with surface tension

---

- ▷ Setup: a 2D elliptical membrane immersed in a fluid at rest
- ▷ Surface tension:  $\mathbf{F} = T \frac{\partial \boldsymbol{\tau}}{\partial s}$ , where  $\boldsymbol{\tau} = \frac{\partial \mathbf{X}}{\partial s}$
- ▷ 2nd order convergence in  $\mathbf{X}$

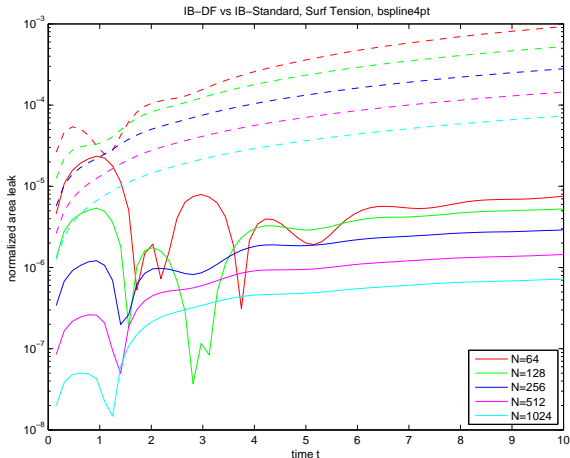
Error in the marker position, Factor = 4, Reparametrized



## A 2D membrane with surface tension

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- ▷ Setup: a 2D elliptical membrane immersed in a fluid at rest
- ▷ Surface tension:  $\mathbf{F} = T \frac{\partial \tau}{\partial s}$ , where  $\tau = \frac{\partial \mathbf{X} / \partial s}{|\partial \mathbf{X} / \partial s|}$
- ▷ Volume conservation



## Marker spacing & volume conservation \_\_\_\_\_

- ▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest
- ▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{X}}{\partial s^2}$

## Marker spacing & volume conservation

---

- ▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest
- ▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{x}}{\partial s^2}$
- ▷ Analytic solution:  $\mathbf{u} = 0$ . Any **spurious flow** is numerical error!

## Marker spacing & volume conservation ---

- ▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest
- ▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{x}}{\partial s^2}$
- ▷ Analytic solution:  $\mathbf{u} = 0$ . Any **spurious flow** is numerical error!
- ▷ Investigate the relationship between marker spacing (# of markers per mesh-width) and volume conservation



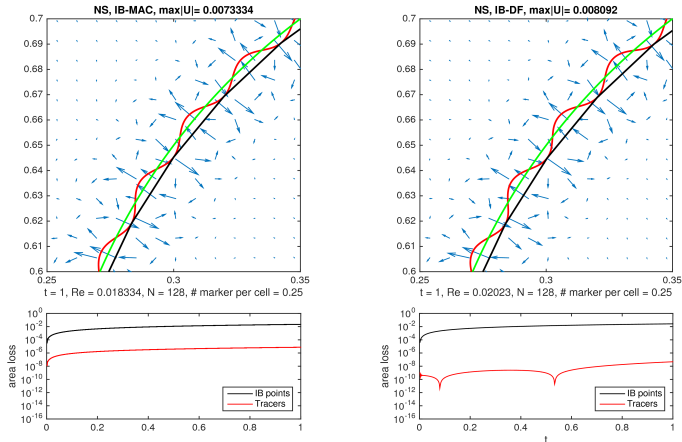
## Marker spacing & volume conservation

---

▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest

▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{X}}{\partial s^2}$

0.25 marker per meshwidth (4 meshwidth between two IB markers)



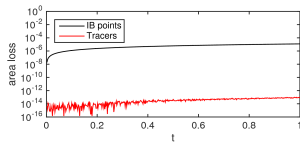
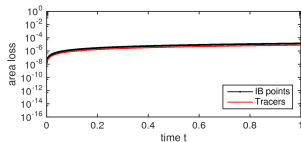
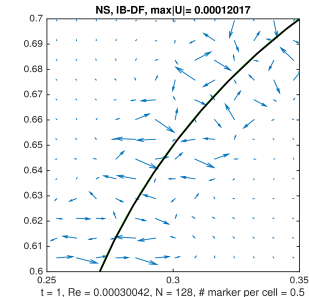
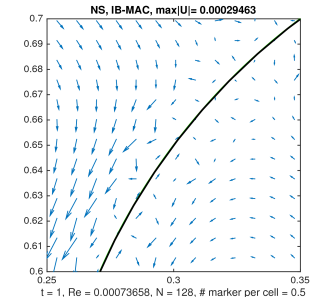
## Marker spacing & volume conservation

---

▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest

▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{X}}{\partial s^2}$

0.5 marker per meshwidth (2 meshwidth between two IB markers)



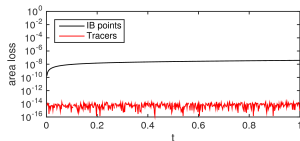
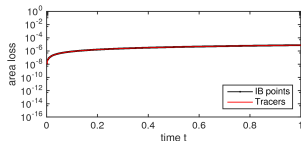
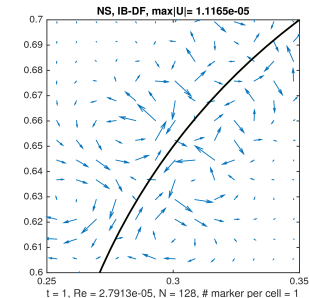
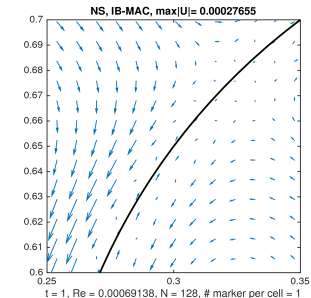
## Marker spacing & volume conservation

---

▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest

▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{X}}{\partial s^2}$

1 marker per meshwidth



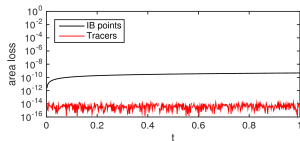
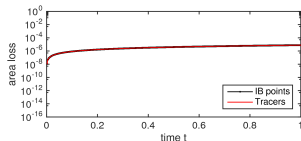
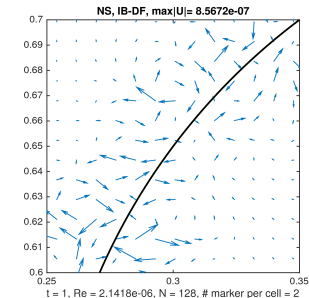
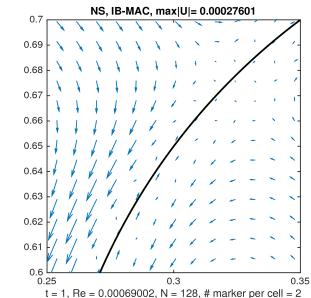
## Marker spacing & volume conservation

---

▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest

▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{X}}{\partial s^2}$

2 markers per meshwidth



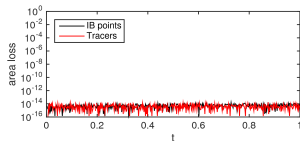
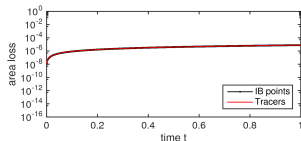
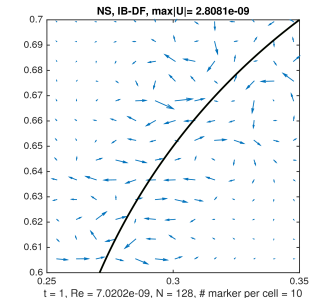
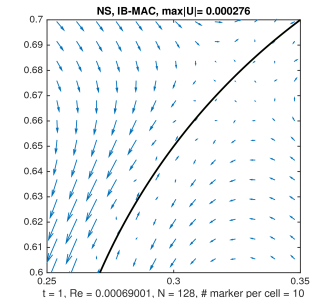
## Marker spacing & volume conservation

---

▷ Setup: a 2D circular membrane (equilibrium) immersed in a fluid at rest

▷ Force density  $\mathbf{F} = \frac{\partial^2 \mathbf{X}}{\partial s^2}$

10 markers per meshwidth



## In Closing

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- ▷ **Divergence-free** velocity interpolation & force spreading
  
- ▷ Improved volume conservation & accuracy
  
- ▷ A new  $C^3$  6-point discrete delta function
  
- ▷ Remark: discretely divergence-free force spreading  $\mathbf{f}(\mathbf{x}) \implies \mathbf{f}(\mathbf{x})$  includes the pressure gradient that is generated by Lagrangian forces. not yet clear how to isolate  $\nabla p$  from force spreading (advantage or disadvantage?)